Surface Roughness Measurements of Cylindrical Gears and Bevel Gears on Gear Inspection Machines

Günter Mikoleizig

Alongside the macro test parameters on tooth flanks for profile and tooth traces, surface properties (roughness) play a decisive role in ensuring proper toothed gear function. This article addresses roughness measurement systems on tooth flanks. In addition to universal test equipment, modified test equipment based on the profile method for use on gears is addressed in particular. The equipment application here refers to cylindrical gear flanks and bevel gear flanks. The most important roughness parameters, as well as the implementation of the precise measurement procedure will also be described under consideration of the applicable DIN EN ISO standards as well as the current VDI/VDE Directive 2612 Sheet 5.

Introduction

Alongside the macro test parameters on tooth flanks for profile and tooth traces, surface properties (roughness) play a decisive role in ensuring proper toothed gear function. The generally increased load stresses on gear teeth can only be implemented by maintaining precisely defined roughness parameters. Roughness measurements are therefore conducted on the gearing flanks in all highly developed drives, in the automotive industry, aircraft industry, or the area of wind energy drives, for example.

This article addresses roughness measurement systems on tooth flanks. In addition to universal test equipment, modified test equipment based on the profile method for use on gears is addressed in particular. The equipment application here refers to cylindrical gear flanks and bevel gear flanks. The most important roughness parameters, as well as the implementation of the precise measurement procedure will also be described under consideration of the applicable DIN EN ISO standards as well as the current VDI/VDE Directive 2612 Sheet 5.

The Purpose of Roughness Measurement on Toothed Gear Flanks

Alongside the macro test parameters on tooth flanks for profile and flank lines, surface properties (roughness) play a decisive role in ensuring proper toothed gear function. Unlike general functional surfaces, the particular shape (curvature) and the slide-roll effect during meshing come into play with tooth flanks. Thus the surface roughness affects the following properties:

- Flank load capacity
- Tooth root load capacity
- Wear load capacity
- Load capacity involving heavy scoring
- Lubrication conditions
- Noise behavior
- Approach behavior

When determining the gearing quality according to DIN/AGMA/ISO standards

via profile and tooth trace, an impression of the existing roughness is also obtained, but this is in no way comparable to roughness measurement performed according to the standard. The correlation is clear when the various probe elements for the measurement are taken into account, for example (Fig. 1). A standard gear measurement is performed with a 1.5 mm probe (radius 750 μ m); for a roughness measurement, however, a diamond tip with a radius of 2 μ m or 5 µm is used. A roughness measurement therefore measures significantly finer structures on the surfaces. Along with the macro test parameters on tooth flanks



Figure 1 Comparison of measuring results.

Printed with permission of the copyright holder, the American Gear Manufacturers Association, 1001 N. Fairfax Street, Fifth Floor, Alexandria, VA 22314-1587. Statements presented in this paper are those of the author(s) and may not represent the position or opinion of the American Gear Manufacturers Association.

according to the gear standards for cylindrical gears, surface properties (roughness) plays an important role in ensuring a proper toothed gear function.

Overview of Roughness Parameters

The general roughness parameters are defined in the DIN EN ISO 4287 standard. An application of this standard for tooth flank measurements is described in the current VDI/VDE 2612 Sheet 5. In a general roughness measurement, the unfiltered P profile (Ref. 2) is obtained initially. Filtering then produces the longwave deviation (W profile) or the shortwave deviation (R profile). The shortwave deviations form the basis for the general roughness parameters used (Fig. 2).

During filtering of the recorded profiles, DIN ISO 16610-21 specifications apply, including measuring paths and cut-off wavelength (Fig. 3).

The profiles relevant for the roughness measurement are limited by the lambda C filter (waviness cut-off) and the lambda S filter (cut-off for even finer structures) (Fig. 4).

The most important roughness parameters for flank measurements are shown in Figure 5.

The arithmetic mean roughness value *Ra* is the ordinate value of the roughness profile within a single measurement path *lr*. The individual roughness depth *Rz* is the sum of the distance between the profile peak and profile valley within a single measurement path *lr*. Like *Ra*, the averaged roughness profile *Rz* is determined as an arithmetic mean from the individual and measurement paths.

The total height of the roughness profile *Rt* is the sum of the height of the largest profile peak and the depth of the largest profile valley within the measurement path *ln*. The maximum individual roughness depth *Rmax* is the largest individual roughness depths *Rz*. The stock portion *Rmr* is the ratio of the sum of the stockfilled lengths *Ml1-Mli* for the total measuring path ln as a percent value.

The core roughness depth Rk is the depth of the roughness core profile. The reduced peak height Rpk is the height determined from the peaks projecting beyond the core area. The reduced peak depth Rvk is the height determined











Figure 4 Filter parameters and transmission band for roughness profiles.

<u>technical</u>



Figure 5 Roughness parameters according to DIN EN ISO 4287/13565.



Figure 6 Skid less probing system with plane reference.



Figure 7 Probe system with side mounted skid probe (VDI/VDE 2612 Sheet 5).

for the striations extending from the core area into the stock. The parameters Mr1 and Mr2 of the stock percentage curve characterize the stock content at the limits of the roughness profile Mr.

Measuring Methods and Measuring Equipment for Roughness Measurement

In the VDI/VDE 2602 directive, and the DIN EN ISO 4287 and DIN EN ISO 16610-21 standard, these are profile methods that describe the properties of the profile equipment and the generalcase measurement conditions for roughness measurements of surfaces.

Skid-less probing systems and instruments with lateral skid (at the side off) are typically used to measure flank roughness (Ref. 1).

Figure 6 shows the tracing situation of a skid-less probing system in the tooth space. The profile here must be aligned as parallel as possible to the tracing direction of the test device. In the result, however, there is always a difference between the straight trace direction and the curved flank. The overall profile must therefore be corrected with a compensation arc, or residual errors must be eliminated with the lambda C profile filter. The possible trace path is limited due to the curved profile surface and the measuring range of the roughness probe.

The probing conditions of a skid system are shown in Figure 7. The sidemounted probe skid follows the profile of the tooth flank. A deviation due to changing contact conditions during the roughness measurement must be taken into account here. The deviations are relatively small, however, and are largely eliminated due to profile filtering.

For roughness measurement on cylindrical gear flanks, measuring devices with an involute reference (Fig. 8) offer certain advantages. Logging of measured values in profile generation mode on the tooth flank (involute) ensures that the probe tip is always aligned perpendicular to the surface; thus the roughness can theoretically be scanned over the entire profile length. The disadvantage of this type of contact operation, however, is that the scanning speed for measured value logging is not constant, nor is a uniform measuring point distance ensured. But this is a minor disadvantage, resulting in measured value differences of up to 10%.

On current gear measuring centers, the involute reference is generated via CNC path control and can be used in principle in conjunction with skid-less systems and skid systems. For special profiles and bevel gear flanks with other profile forms, for instance, the CNC-guided path control can also execute reference profiles.

Roughness Measurement Procedure in Practice

The measuring conditions (Ref. 1) must first be defined in order to achieve generally comparable results. The following points must be taken into account to avoid measurement deviations:

- Probe system
- Profile filter
- Alignment of test specimen •
- Environmental influences

Refer to Table 1 to select appropriate individual measurement paths and cutoff. As finish-machined surfaces on tooth flanks in particular must be tested, the highlighted values should be used preferentially. The measuring direction for the roughness measurement should be selected according to Table 2, based on the machining method and the resulting structures.



Figure 8 Skid probe system with involute reference (VDI/VDE 2612 Sheet 5).

Table 1 Selection periodic	on of individual m c profile	neasuring paths/c	ut-offs accord	ing to DIN EN ISO 4288				
Periodic profile	Non-perio	dic profile	Cut-off ¹⁾	Sampling length (<i>Ir</i>)/				
RSm , mm	Rz , μm	Ra , μm	λ c, mm	<i>Ir/In</i> , mm				
> 0.013 to 0.04	> -0.025 to 0.1	> -0.006 to 0.02	0.08	0.08/0.40				
> 0.04 to 0.13	> 0.1 to 0.5	> 0.02 to 0.1	0.25	0.25/1.25				
> 0.13 to 0.4 ²⁾	> 0.5 to 10 ²⁾	> 0.1 to 2 ²⁾	0.80 ²⁾	0.8/4.0 ²⁾				
> 0.4 to 1.3	> 10 to 50	> 2 to 10	2.5	2.5/12.5				
> 1.3 to 4.0	> 50 to 200	> 10 to 80	8.0	8.0/40				
NOTES:			100 4000					

Sampling length, evaluation and cut-off according to DIN EN ISO 4288

2) Suitable parameters for grounded gears



technical

When selecting the appropriate parameters for the roughness measurement on tooth flanks, the stress on these surfaces due to compression and sliding must be taken into account. The parameter Rmax has little meaning for this stress, as individually projecting peaks, which are of little relevance for the load capacity, are taken into account here. The arithmetic mean raw value Ra is greatly distributed, but correlates the least with the function parameters and therefore should not be used. The preferred parameter for roughness on flank surfaces is Rz, as it provides a high degree of clarity and makes it possible to draw accurate conclusions about the height of the roughness profile.

In addition to the parameters that describe only the vertical expansion of the roughness profile, it is important to determine the roughness structure in order to determine the wear behavior or load capacity of a tooth flank. The stock percentage curve (Abbott-Firestone) and the resulting parameters Rk, Rpk and Rvk are appropriate for determining the structure of the roughness profile. A nearly S-shaped pattern in the stock percentage curve is ideal. Another appropriate parameter for the stock percentage is Rmr (c). See Table 3 for a comparison of roughness parameters and stock percentage curves.

A standard roughness testing device (Ref. 3) is shown in Figure 9. In addition to a feed mechanism with a microprobe system, the device also features a cross-slide to position and test the workpiece. An additional clamping fixture is generally needed to test toothed gears. According to the figure detail, compact reference area probe systems with an application range from module 0.5 can be used here. A PC computing system with high-performance software is available to control and evaluate the roughness measurements. The evaluation software takes into account a large number of established roughness measurement standards. A report printout of the measuring results can be custom-designed.

One advantage of the device presented is that general workpieces can also be tested, and a higher standard overall is provided for roughness measurement. It does, however, require more set-up for flank measurements and the device is not suitable for large and heavy workpieces (500 mm in diameter, for example).

Application example: cylindrical gear/ bevel gear measurement on gear measuring centers. Gear measuring centers are typically equipped with a rotary table for testing rotationally symmetrical workpieces and are suitable for measured value logging on small to very large

Table 3 Evaluation of roughness profiles a	and asso	ociated sto	ck perco	entage cu	rves	
Roughness profile	Rt	Rmax	Rz	Ra	Rmr (0.25)	Abbott curve
<u>NRRRRR</u>	1	1	1	0.25	75%	11/1/11
ALLAA	1	1	1	0.25	15%	James
	1	1	1	0.20	85%	
Andredon Andredon Andre	1	1	1	0.20	20%	Turner
YTTTYYYYYY,	1	1	0.4	0.08	88%	
mmhimm	1	1	0.4	0.08	7%	Long
3.17.17.17.	1	1	1	0.20	25%	Timm
AAAAAAAAAAAAA	1	1	1	0.30	38%	0 % 100 %
NOTES: + Ra ++ Rz +++ Rk, Rpk, Rvk						

workpieces, in conjunction with a model series. As previously described, the measuring method used here is the involute reference in combination with a skid system.

For roughness measurement a special probe system on the adapter plate of the measuring machine's macro probe system is adapted (Fig. 10). An additional electrical connection is provided for transferring the measured values from the integrated micro-probe system for the roughness measurement. For measured value logging in the profile direction, the probe skid rests on the flank to be tested and executes a movement similar to a normal profile measurement for the macrostructure of the flank. As it does so, a diamond needle located in front of the probe skid logs the measured values for the roughness measurement. The probe system represented here is also suitable for measured value logging in the tooth trace direction. The roughness probe system also features an adjustment mechanism enabling the probe needle to be aligned perpendicular to the surface for helical cylindrical gears as well.

Thus in conjunction with an automatic probe change rack, a fully automatic process can be carried out for the roughness measurement in combination with other gear measurements. Because the measured value logging is controlled by the CNC-guided measuring axes, this results in highly precise positional accuracy and reproducibility for the measuring positions. The most important technical data for the integrated roughness test equipment are shown in Table 4.

To document the measuring results, the roughness parameters can also be documented on the standard measuring sheet for profile and reference tooth traces, or they can be printed as a separate measuring sheet including diagrams (Fig. 11).

Comparable to measured value logging on cylindrical gears, roughness measurements can also be conducted on bevel gears. The profile measurement here takes place based on the calculated nominal data, which are available in high resolution for measuring the macrostructure. Various probe systems are used for measured value logging, depending on



Figure 9 Standard roughness test device — example stationary surface measuring station for gears (Mahr catalog).



Figure 10 Roughness testing device (cylindrical gear) on gear measuring centers—roughness inspection in profile direction (involute reference).

Table 4 Technical data f	or roughness probe systems										
Length Lt (mm)	1.5	4.8									
Cut-off filter λc (mm)	0.25	0.8									
Technical data:											
Device class to DIN EN ISO 3274 (DIN 4772), Class 1											
Output values to DIN EN IS	SO 4287 (DIN 4762), Ra, Rz (D	IN), Rt, Rmax									
Resolution: <i>Ra</i> 0.01 µm (< 0).1 µm: 0.001 mm), all other pa	arameters: 0.1 µm									
Cut-off filter <i>\lacepseloc</i> to DIN EN I	SO 11562: phase correct dig	ital Gaussian filter (M1)									
Sampling length <i>Lt</i> /Cut-off	filter λc (fixed correlation										
Micro-roughness filter λ <i>c</i> :	2.5 µm										
Evaluation of single measu	ured lengths										
Skid radius: lengthwise 10	mm, crosswise 1.0 mm										
Feed rate <i>vt</i> : 0.5 mm/sec											
Static probe force on the s	sliding skid: < 200 Nm (< 20 g)									
Static measuring force on	the probe tip: < 0.5 Nm										
Probe tip: diamond, conica	al form										
Probe tip radius: 5 µm											
Probe tip angle 90°											
Offset between probe tip a	and sliding skid: lengthwise 1	mm, crosswise 0 mm									
Maximum measuring strol	ke of probe tip: ±100 mm										

			Gea	r P	rof	11	le/				Gear	Rot	lghne	88		
							4	Gear Roughness Image: dBT0410cc5 - 3 P 65 maxetime: V. Bchablousky Image: Mello m. et maxetime: V. Bchablousky 3 Image: Mello m. et maxetime: V. Bchablousky 3 Image: Mello Mello 3 4 Image: Mello Mello 3 4 Image: Mello Mello 3 3 Image: Mello Mello 3 4 Image: Mello Mello 3 3 Image: Mello Mello 3 4 4 Mello Mello 3 4 4 Mello Mello 4 4 4 Mello Mello 4 4 4 Mello<								
From Mo. 1	GST0410	005 -1	P 65		Onerster		¥ 8/	37941	m. of tests 9							
		0110			- operation		V. 00	Securing Ha. :	module m 3m							
iyya: HELLE					No. of testh		Coder Hour	4		Pressure angle			14.8			
Prewing Ho.: Welle Gang1					Module m	Module m						Salts sigle 26.6"				
Order No. :	5				Pressure	angle		Lie. of chack-	KIII	geinberg		Base Cár 2 @ 28.9584m				
Cust. /Hach.	Mari X	L P65 6	03009		Hally and			Condition	1.1.1.1	1.1.1.1	In the local sector	Bare Belta angle 25.6				
tes of check, Klingelnherg					left flank -						flank the	1	ROFILE		r	
Condition					Bass Reld		1.	Tip			1			1	+	
DTN 3960								+++		1 3			-3	+		
		3	lett IIa	nk < 2		RO	LIPR	5			3			15		
		11/	11	10		L.F.	- 14.10	1 Jun	1 - 1					12	T	
Tip		+	++	4	A		12.78	Va2000:1			1 3			18		
		1	V I	1	1	_					8			15		
	14 9.5	111	1	8	1	-		Vb46:1			3			15	T	
. 10 .	111 101 101	1			1	1		.22	11		1 3			18		
N 1100		2	1 +++	6	1		11.92	mt			3			3	T	
Pro	F-1 - 1	61		6	1	also a		Root			1 2	Lter:	5mm [3000]	13	T	
		Y I					1.1.1				1	114	Tooth	13		
	Here of the based			Constant's	and the second s	1.000	1		Act.	alue (pm)	Quality	Lin	value Qua	1	Act	
								Ra			0.25			0.2	8	
	1 2 2			2 1	T			8.0			1.41	-		1.4	2	
Isan	1.2 2	1.0	1 0 0 0	1				Rt			1.63			2.1	9	
t Ha.	0.9	1.8	2.0 3	-0.1	±45	5	14.5	834	-		0.74	-		0.7		
Pa.	3.9	4.4	4 4.1	4.3	7	5	7	Rg			0.30	-		0.3	5	
ffa	4.5 5	4.4	4.0	4.2	6	5	6	April 1/ord			416.0			376.	0	
la/s/t/max	0.25	1.40	1.64	1.58	Lt	= 1.	.5mm	88.			1.13	_		1.1	2	
/T-minal	26.380)	[26.9	9/27.01	1	C REAL PROPERTY.		Rpix	-		0.08	-		0.2	5	
direction 1			1.0.1.5		-			RVK			0.32			0.5	0	
								THAT AL	-		90.76	-		- A.A.	*	

Figure 11 Results output: roughness measurement on gear measuring centers.



Figure 12 Roughness testing device (bevel gear) on gear measuring centers.

the design of the bevel gears pinions/ ring gears. For pinion shafts a straight probe system is used — exactly like the probe system for cylindrical gears (Fig. 12) — and an angled system is used for ring gears.

A fully automatic test sequence can also be specified via the software operator guidance. Measuring positions, measuring paths, and the number of flanks to be tested, etc., can be programmed individually (Fig. 13). The measuring results are displayed numerically on the screen for the selected flanks (Fig. 14); measured values can also be printed out with diagrams (Fig. 15).

Thus the device presented here offers a reliable, convenient measuring method for roughness measurement on spiral bevel gears with spatially pronounced curves. Large-module bevel gears can also be tested in conjunction with suitable probe systems.

Concluding Remarks

These important measured values can be carried out quickly and easily in conjunction with conducting roughness measurements of tooth flanks on gear measuring centers using the equipment presented here.

Measurements on both smaller and larger gear teeth can be taken in a single



Figure 13 Operator guidance: roughness measurement on gear measuring centers.

Measurin Length (ng position of tracelin	: E4; R: e (Lt):	86.093,3 1.500 mm	Z: 21.409 Cutoff	9 mm filter	(Lc): 0.:	250 mm								
Tooth	Flank	∣Ra ∣µm	Rz(DIN) µm	Rt µm	∣Rmax µm	R3z µm	Rq µm	Rpc 1/cm	Rk µm	Rpk µm	R∨k µm	MR1 %	MR2 %	∣R∣ µm	AR µm
1	concave	0.96	6.01	8.42	7.29	1.98	1.27	240.00	3.62	0.69	2.45	0.44	83.3	0.00	0.00
1 1	convex	0.66	3.66	4.81	4.44	0.98	0.84	232.00	2.61	0.37	1.33	0.40	83.9	0.00	0.00
14	concave	1.04	6.07	8.23	7.15	2.32	1.33	232.00	3.89	0.56	2.50	0.20	83.1	0.00	0.00
14	convex	0.52	3.17	4.77	4.00	1.11	0.66	208.00	2.28	0.58	1.03	10.36	89.7	0.00	0.00
28	concave convex	0.87	4.10	6.24	7.25 5.91	2.09	1.12	176.00	2.36	0.39	2.15	0.64	85.3	0.00	0.00
Mean	concave	0.96	5.92	8.01	7.23	2.13	1.24	274.67	3.65	0.55	2.28	0.43	183.9	0.00	0.00
Mean	convex	0.63	3.64	5.27	4.78	0.70	0.81	205.33	2.42	0.43	1.50	0.49	85.5	0.00	0.00
Mean	cv.+cx.	0.79	4.78	6.64	6.01	1.41	1.02	240.00	3.03	0.49	1.89	0.46	84.7	0.00	0.00
• • • • • •			• • • • • • • •	• • • • • • • •		• • • • • • • •			• • • • • • • •					• • • • • • •	

Figure 14 Results output: roughness measurement on gear measuring centers.



Figure 15 Roughness bevel diagram.

clamping in conjunction with standard test parameters.

The measurement conditions for standardized roughness measurements are largely met by measured value logging in the profile direction with CNCcontrolled contouring in generation mode for each tooth profile.

References

- 1. VDI/VDE 2612; Sheet 5. Measurement and Testing of Gearings: Surface Roughness Measurement of Cylindrical Gears and Bevel Gears by Means of Stylus-Type Instruments (Release 2014/2015).
- 2. Jenoptik publication.
- 3. Mahr publication. "Mar Surf XR 20 Roughness Testing Device."

Dipl.-Ing. Guenter Mikoleizig currently heads the product management and application engineering department for gear inspection machines at Klingelnberg GmbH, Germany. With more than 30 years in the field of gear inspection technology, he is fully experienced with the design and development of inspection machines and their product management. He in fact developed a product line of inspection machines for an array of gears and related parts, with small dimensions up to the very large-sized.



Mikoleizig has presented papers about gear inspection worldwide and is also an active member of national and international standardization committees.

