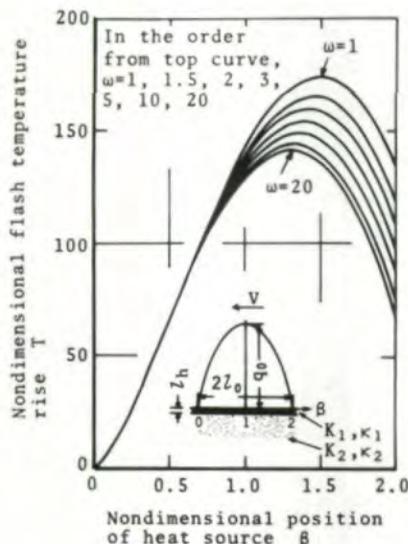


(a)  $\delta=0.001$ ,  $L=5000$



(b)  $\delta=0.01$ ,  $L=5000$

Fig. 2—Relation between nondimensional flash temperature rise and nondimensional position of heat source

nion and the wheel, respectively. The distribution of heat intensity is assumed to be parabolic. Therefore, the value of  $q_0$  is given by,

$$\mu \delta_0 P_n |V_1 - V_2| = 4q_0 l_0 / 3 \quad (2)$$

The equations of the surface temperature at the meshing faces of the pinion and the wheel are derived from equation (1) as follows:

$$\left. \begin{aligned} \theta_{f1} &= \frac{2\kappa_{11} q_0}{\pi K_{11} V_1} T_1 \\ \theta_{f2} &= \frac{2\kappa_{12} q_0}{\pi K_{12} V_2} T_2 \end{aligned} \right\} \quad (3)$$

junctional area into the mating teeth of the pinion and the wheel are expressed by  $\psi$  and  $1 - \psi$ , the surface temperature at the meshing faces of the pinion is equivalent to that of the wheel. Therefore, the value of  $\psi$  is given by

$$\psi = \frac{\kappa_{12} K_{11} T_2}{\kappa_{11} K_{12} T_1 V_2 / V_1 + \kappa_{12} K_{11} T_2} \quad (4)$$

The surface temperature at the meshing faces is given by

$$\theta_f = \frac{\kappa_{12} T_1 T_2}{\kappa_{11} K_{12} T_1 V_2 / V_1 + \kappa_{12} K_{11} T_2} \frac{2\kappa_{11} q_0}{\pi V_1} \quad (5)$$

### Calculated Results

For example, Figs. 2(a) and (b) show the relation between the flash temperature rise and the position of the heat source, expressed in terms of the dimensionless parameters  $T$  and  $\beta$ , respectively. In this figure,  $\omega=1$  indicates that the thermal properties in the surface layer are equivalent to those in the core, and the maximum value of  $T$  occurs at  $\beta=1.5$ . In contrast,  $\omega>1$  indicates that the thermal properties in the surface layer are worse than those in the core. The maximum value of  $T$  occurs at  $1<\beta<1.5$ , and the position where the maximum value of  $T$  appears moves toward the vicinity of the center of the heat source with an increasing value of  $\omega$ .

Figs. 3(a) and (b) show the relation between the maximum

### Nomenclature

- $a$  = acceleration due to oscillation of gear box,  $m/s^2$
- $g$  = gravitational acceleration =  $9.8 m/s^2$
- $K_1$  = thermal conductivity in the surface layer of gear tooth,  $W/(m K)$
- $K_2$  = thermal conductivity in the core of gear tooth,  $W/(m K)$
- $L$  = nondimensional velocity of heat source =  $V l_0 / (2\kappa_1)$
- $l_h$  = thickness of surface layer,  $m$
- $l_0$  = a half of the band length of Hertzian contact zone,  $m$
- $n_1$  = rotational speed of pinion, rpm
- $P$  = normal load per unit ball,  $N$
- $P_n$  = normal load per unit face width,  $N/m$
- $q_0$  = maximum value of heat intensity generated per unit time,  $W/m^2$
- $T$  = nondimensional flash temperature rise =  $\pi K_1 V \theta_f / (2\kappa_1 q_0)$
- $V$  = sliding velocity,  $m/s$
- $\beta$  = nondimensional position of heat source =  $rV/l_0$
- $\delta$  = nondimensional thickness of surface layer =  $l_h/l_0$
- $\delta_0$  = load-sharing
- $\theta_f$  = flash temperature rise,  $K$
- $\theta_0$  = bulk-temperature,  $K$
- $\kappa_1$  = thermal diffusivity in the surface layer of gear tooth,  $m^2/s$
- $\kappa_2$  = thermal diffusivity in the core of gear tooth,  $m^2/s$
- $\mu$  = coefficient of friction
- $r$  = time,  $s$
- $\omega$  = ratio of thermal contact coefficient of surface layer and core =  $(K_2/\sqrt{\kappa_2})/(K_1/\sqrt{\kappa_1})$

(continued on page 22)

When the rates of the heat quantity flowing from the con-

**THE NEW GLEASON**  
**G-MAXX™**  
**BEVEL GEAR GENERATOR**



Visit us at IMTS Booth #6333 McCormick North

# THE FIRST TRULY UNIVERSAL BEVEL GEAR GENERATOR EVER MADE

First ever CNC bevel gear generator.

First with two *and* three axis geometries.

First with such superior machine accuracy.

The new Gleason G-MAXX™ 2010 bevel gear generator can give you strong, quiet, high quality gears more productively, more cost efficiently than any other generator ever made.

## First In Flexibility

You get three axis geometry for quick, accurate, continuous hobbing. You get a completed gear and pinion in one chucking.

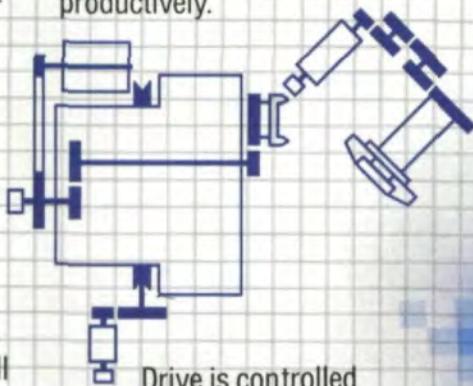
You also get two axis geometry for cutting, grinding and hard finishing by the intermittent face mill process.

The new Gleason G-MAXX generator is designed to either stand alone or function in an automated systems manufacturing environment.

No other generator ever made gives you such choices.

## First In Electronics

You program and store your machine settings with Computerized Numeric Control. CNC controls the speed and position for cutter, cradle, workspindle, and sliding base to drastically reduce your set-up time. You can handle smaller, more diverse runs more productively.



Drive is controlled electronically, not mechanically. Just 14 gears precisely transmit all motion. A shorter drive train maximizes the accuracy and finish of your gear.

## First In Tooling

For continuous hobbing, alternate blade design of our exclusive TRI-AC™ cutter allows for more blade groups per head. You can cut far faster than with conventional cutters. Coated front blade surface reduces tool wear so you can cut far more pieces before sharpening. When you do sharpen, coating stays intact. You get a higher quality finish that requires up to 50% less lapping time.



## First In Savings

It all adds up. Prime flexibility, CNC control, high accuracy, fast setup, and high quality gear sets can elevate your productivity to greatly diminish your overall cost per piece. And that's the number one benefit to your bottom line.



## Ask For A First Cut

We'll be happy to run a comparative manufacturing cost analysis based on your bevel gear needs. Talk to your Gleason representative or call us direct. 716-473-1000. Or write Gleason Works, 1000 University Avenue, Rochester NY 14692 USA. See for yourself all the cost efficient solutions the new Gleason G-MAXX 2010 Generator can bring to you.

# GLEASON

G-MAXX and TRI-AC are Trademarks of Gleason Works

CIRCLE A-7 ON READER REPLY CARD

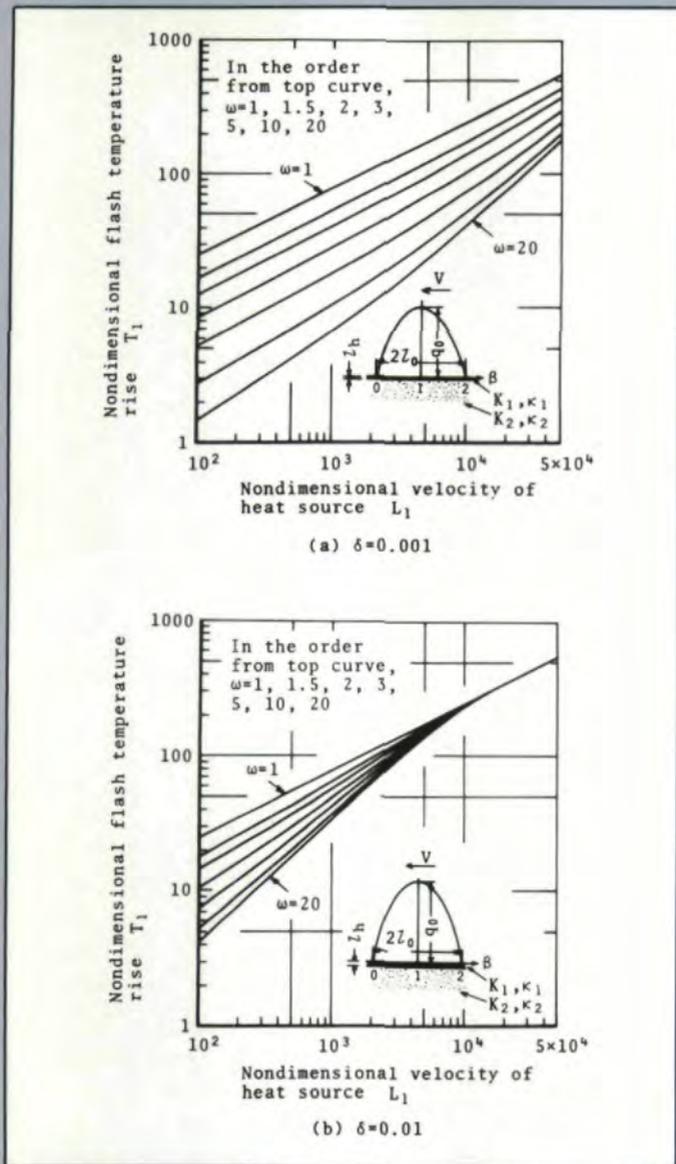


Fig. 3—Relation between maximum value of nondimensional flash temperature rise and nondimensional velocity of heat source

value of the flash temperature rise and the velocity, expressed in terms of the dimensionless parameters  $T$  and  $L$ . When the thickness of the surface layer is smaller than the band length of the Hertzian contact zone as shown in Fig. 3(a), the effect of  $\omega$  on the flash temperature rise is significant. In this article, the tooth surface of the gears was coated with the  $\text{MoS}_2$  film whose thickness was a little larger than the surface roughness  $R_{\text{max}}$  of the tooth surface, and the difference between the thermal properties in the surface layer and those in the core is an important problem. The effect of  $\omega$  on the flash temperature rise decreases with an increasing thickness of the surface layer.

#### Four Ball Tests

For investigating the seizure load and the frictional characteristics of the balls coated with  $\text{MoS}_2$  film, tests have been carried out with a four-ball machine.

**Test Balls.** The diameter and the average sphericity

Table 1 Chemical compositions of ball material

Composition %					
C	Si	P	S	Cr	Mn
0.98	0.32	0.019	0.007	1.40	0.42

Table 2 Combination of ball pairs

		Pair A	Pair B	Pair C	Pair D
$\text{MoS}_2$ coated	Upper ball (Rotating ball)	No	Yes	Yes	No
	Lower balls (Three fixed balls)	No	Yes	No	Yes

of the balls before coating with the  $\text{MoS}_2$  film are 19.05 mm and  $0.18 \mu\text{m}$ , respectively. The chemical compositions of ball material are given in Table 1. The balls were normalized at 443 K after quenched from 1173 K. The surface of the balls before coating had a Vickers microhardness of approximately 800 HV. The balls were coated with the  $\text{MoS}_2$  film that was about  $10 \mu\text{m}$  thick, and the surface roughness of the balls was approximately  $9 \mu\text{m} R_{\text{max}}$ .

**Lubricant.** The balls were lubricated with number 140 turbine oil (a straight mineral oil without additives) with viscosities of  $28 \times 10^{-6} \text{ m}^2/\text{s}$  at 323 K and  $8 \times 10^{-6} \text{ m}^2/\text{s}$  at 363 K, and the oil temperature was controlled to  $293 \pm 2 \text{ K}$  by the thermostat during all tests. The upper ball was immersed about 1/3 diameter deep into the oil bath.

**Experimental Method.** The four ball tests were carried out with stepwise increasing loads (the load  $P$  was increased by about 40 N increments at 30 s intervals) at a constant sliding velocity 0.29 m/s until the seizure of the balls occurred.

The combination of the balls consists of the four types of the ball pairs as shown in Table 2.

#### Test Results and Observations

**Coefficient of Friction.** Fig. 4 shows the relation between the coefficient of friction and the load at the sliding velocity 0.29 m/s. In this figure, the symbol  $S$  indicates the incipience of seizure.

Under comparatively low load ( $P < 0.4 \text{ kN}$  or the maximum Hertzian stress  $p_0 < 3.52 \text{ GPa}$ ), the coefficient of friction between ball pair A was the largest of all ball pairs, and the coefficient of friction between the balls coated with the  $\text{MoS}_2$  film was considerably small. Therefore, the  $\text{MoS}_2$  film is considered to play a significant role in decreasing the coefficient of friction. At the incipient stage of seizure, however, the coefficient of friction between the balls coated with the  $\text{MoS}_2$  film was approximately equal to that between the balls without it since the  $\text{MoS}_2$  film coated on the balls was completely torn out due to wear.

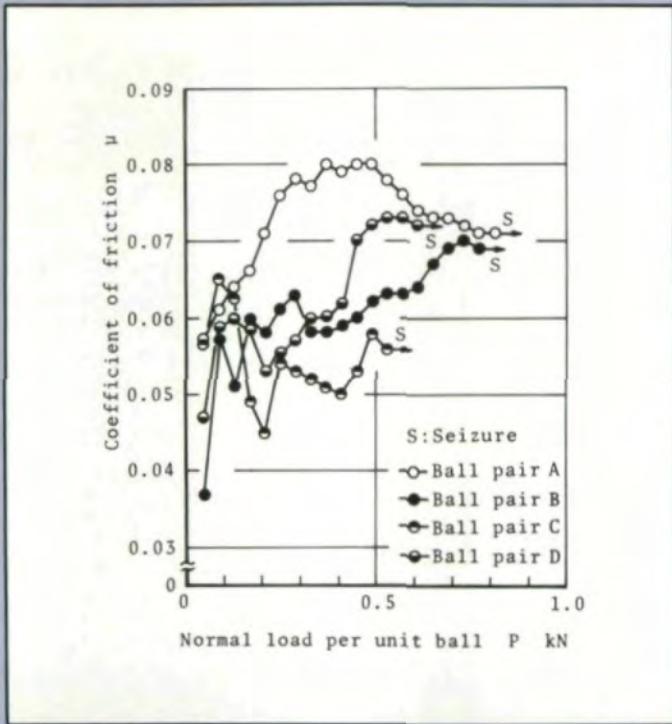


Fig. 4—Relation between coefficient of friction and load

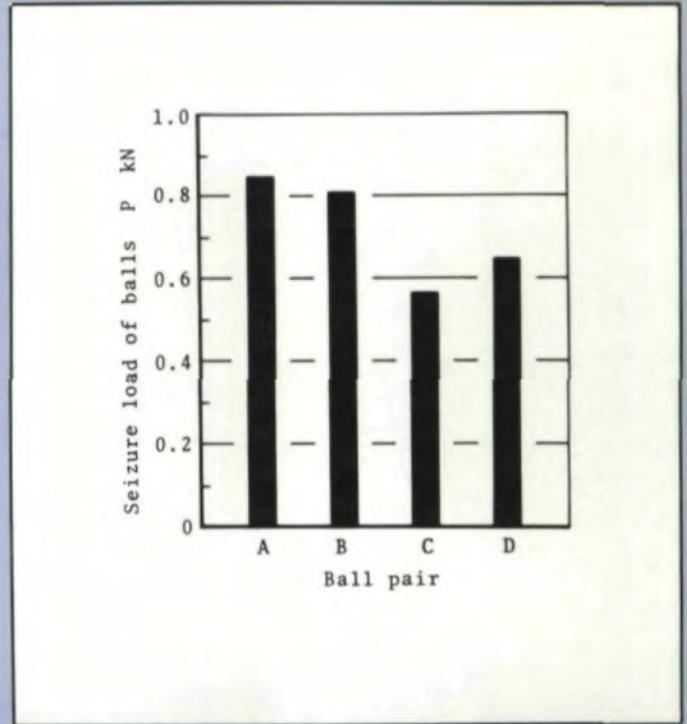


Fig. 5—Seizure load of balls obtained with four-ball machine



**HOGLUND**  
TRI-ORDINATE CORPORATION

## FORMED CBN GEAR GRINDING WHEELS

**GEAR FORMS FROM THE PEOPLE WHO KNOW WHAT AN INVOLUTE IS!**

**NOW AVAILABLE FOR KAPP GEAR GRINDERS**

SPECIALISTS IN GEAR GRINDING TECHNOLOGIES



**FOR YOUR: DETROIT & REDRING GRINDERS**

**HELICALS & SPURS**

HOGLUND TRI-ORDINATE CORP. 343 SNYDER AVE. BERKELEY HTS., N.J. 07922 (201) 464-0200: TWX 710-984-7965



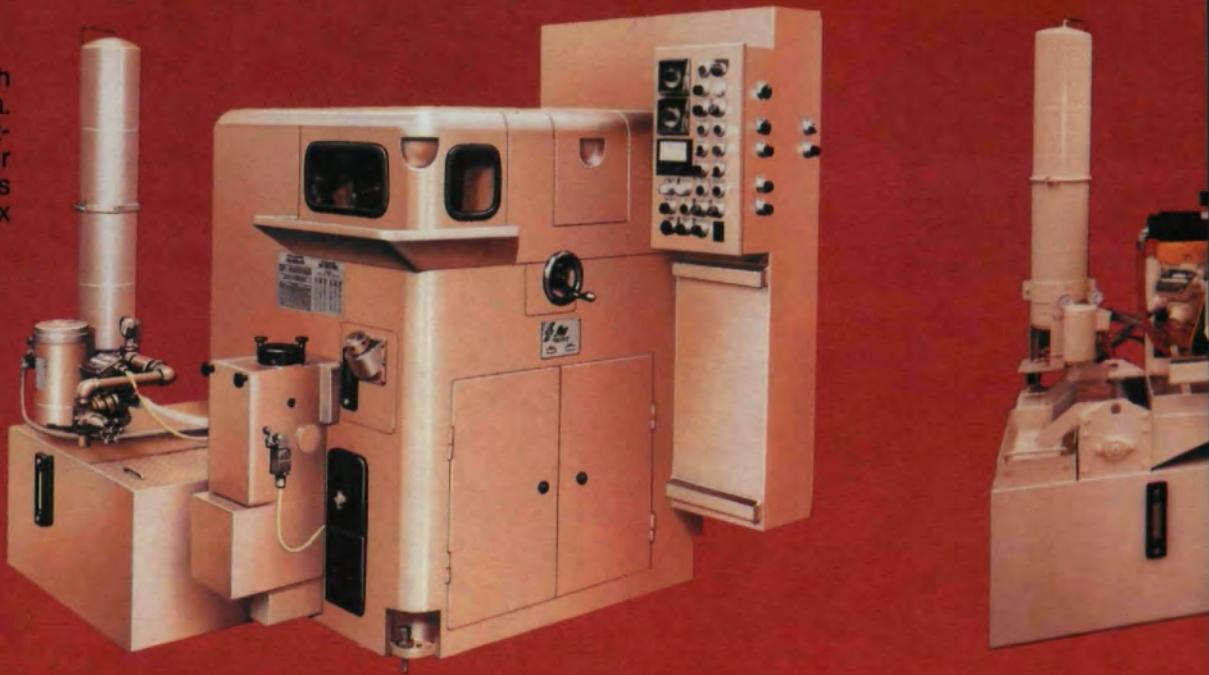
**IMTS**  
Booth #6097  
North Building

CIRCLE A-9 ON READER REPLY CARD

(continued on page 26)

**Vertical Hob  
Sharpener**

For straight gash  
hobs up to 6-in. dia.  
by 6-in. long. Index-  
ing accuracy for  
"Class A" tolerances  
without using index  
plates.



**SHARPENING**

*...the economical and  
for your tool sharpen*

**CNC  
Drill & Reamer  
Sharpener**

This five axis ma-  
chine allows users  
to automatically  
resharpen tools  
to their original  
manufacturing  
specifications.



These domestically manufactured machines have fully programmable automatic grinding cycles and user needs are fully accommodated in their design. We provide on-site engineering service and training to our customers.



### CNC Hob Sharpener

For straight gash hobs up to 10-in. dia. by 12-in. long. Indexing accuracy for "Class AA" tolerances without using change gears or index plates.

**MACHINES**  
*practical solution  
 ing requirements.*

Visit Us at Booth 6343



### Shaper Cutter Sharpener

For both spur type and right- or left-hand helical type shaper cutters. Fully programmable, totally automatic cycles.

## STARCUT SUPPLIED PRODUCTS AND SERVICES

### Star Machine Tools

Standard and CNC Hob Sharpeners  
 Shaper Cutter Sharpeners  
 CNC Drill and Reamer Sharpeners  
 Keyseaters

### Star Cutting Tools

Hobs  
 Form-Relieved Cutters  
 Gun Drills  
 Gun Reamers  
 Keyseat Cutters

### Gold Star Coatings

### Lorenz

Shaper Cutters

### Hurth Machine Tools

Standard & Automatic Keyway and Slot Milling Machines

Automatic Spline Shaft

Milling Machines

CNC Gear Hobbing

Machines

CNC Gear Shaving

Machines

CNC Gear Rolling Machines

Gear Testing Machines

Shaving Cutter Grinding

Machines

CNC Gear Tooth Chamfering

Machines

Gear Deburring Machines

CNC Hard Gear Finishing

Machines

### TiN Coating Systems

Complete Turnkey

Applications

### PLANRING

Planning & Engineering

Flexible Machining Systems

### Stieber

Precision Clamping Tools

*Please contact us for further information on any or all of these sharpening machines and other StarCut supplied products and services.*



CIRCLE A-5 ON READER REPLY CARD

Table 3 Chemical compositions of tooth material

Composition %								
C	Si	Mn	P	S	Ni	Cr	Mo	Cu
0.18	0.28	0.80	0.014	0.019	0.08	0.99	0.16	0.09

Table 4 Data for test gears

	Pinion	Wheel
Number of teeth $z$	18	40
Center distance mm	116	
Pressure angle $\alpha_0$	20°	
Module $m$ mm	4	
Backlash $S_n$ mm	0.5	
Face width $B$ mm	10	
Effective face width $B_f$ mm	7	
Tooth profile	Standard	
Pitch circle diameter $d_0$ mm	72	160
Outside diameter $d_1$ mm	80	168
Contact length mm	19.15	
Contact ratio $\epsilon$	1.62	
Material	SCM 415H	

**Seizure Load.** Fig. 5 shows the variation in the seizure load of the balls coated with the MoS<sub>2</sub> film or without it. The seizure load of the balls with ball pair B was not so much different from that with ball pair A, and little effect of the MoS<sub>2</sub> film could be recognized on the seizure load of the balls. Further, with ball pairs C and D, the seizure load of the balls was smaller than that with ball pair A, and it rather decreased due to the coating of the MoS<sub>2</sub> film.

**Gear Tests**

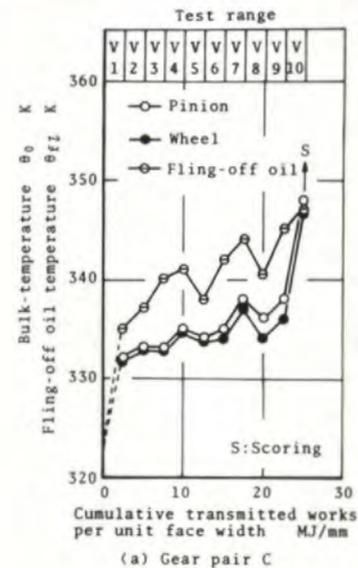
Scoring tests of the gears coated with MoS<sub>2</sub> film were run with a power-circulating gear machine. The effect of the MoS<sub>2</sub> film on the scoring resistance of the gears was investigated.

**Test Gears.** The test gears were made of chrome-molybdenum steel and case-hardened by gas-carburizing. The chemical compositions of tooth material are shown in Table 3. The working surface of the gears had a Vickers microhardness of approximately 720 HV. The gears were ground by a gear grinding machine as shown in Table 4. The single-pitch error and the tooth profile error of the gears were approximately 2  $\mu$ m before coating with the MoS<sub>2</sub> film. The accuracy of the tooth profile of the gears before coating was of zero class, according to the Japanese Industrial Standard JIS B 1702. The surface roughnesses along the tooth trace of the pinion and the wheel before coating were about 2  $\mu$ m  $R_{max}$ .

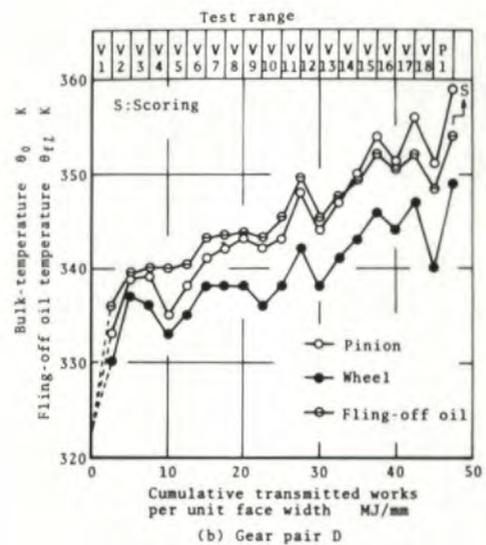
The combination of the gears consists of the four types of the gear pairs as shown in Table 5. The gear teeth were coated

Table 5 Combination of gear pairs

	Pair A	Pair B	Pair C	Pair D
MoS <sub>2</sub> coated Pinion	No	Yes	Yes	No
MoS <sub>2</sub> coated Wheel	No	Yes	No	Yes



(a) Gear pair C



(b) Gear pair D

Fig. 6—Variations in bulk-temperature of gear teeth and fling-off oil temperature

**Experimental Method.** The scoring tests were carried out with the MoS<sub>2</sub> film that was about 10  $\mu$ m thick after grinding, and the surface roughness after coating was approximately 9  $\mu$ m  $R_{max}$ .

**Lubricant.** The test gears were lubricated with the same oil used for the four ball tests. The oil was sprayed onto the meshing faces at a rate of 0.6 L/min. The oil temperature was controlled to 323  $\pm$  2 K by the thermostat during all tests.

Table 6 (a) Speed data

Speed range	V-1	V-2	V-3	V-4	V-5	V-6	V-7	V-8	V-9	V-10	V-11	V-12	V-13	V-14	V-15	V-16	V-17	V-18
Rotational speed of pinion $n_1$ rpm	2000	2310	2644	3001	3381	3783	4208	4655	5125	5618	6133	6671	7231	7814	8420	9048	9699	10372
Peripheral velocity m/s	7.5	8.7	10.0	11.3	12.7	14.3	15.9	17.6	19.3	21.2	23.1	25.2	27.3	29.5	31.7	34.1	36.6	39.1
Cumulative transmitted works * MJ/mm	2.5	5.0	7.5	10.0	12.5	15.0	17.4	19.9	22.4	24.9	27.4	29.9	32.4	34.9	37.4	39.9	42.4	44.9

\* The cumulative transmitted works are defined as the sum of the transmitted works per unit face width at the respective test ranges.

Table 6 (b) Load data

Load range	P-1	P-2	P-3	P-4	P-5	P-6	P-7	P-8	P-9	P-10
Tooth load $P_n$ N/mm	278	290	302	314	327	339	352	364	377	390
Cumulative transmitted works MJ/mm	47.5	50.2	53.0	55.9	59.0	62.2	65.4	68.8	72.4	76.0

at stepwise increasing pinion speeds from V-1 to V-18 as shown in Table 6(a). The increment of the calculated value of the flash temperature rise was the same for the respective speed ranges under a constant load of  $P_n = 266$  N/mm. When surface failure by scoring was not observed up to the speed range V-18, the tests were continued with stepwise increasing loads at a constant pinion speed of  $n_1 = 10372$  rpm as shown in Table 6(b). The increment of the flash temperature rise per unit load range corresponds to that of the flash temperature rise per unit speed range.

The tests were run until the total number of pinion revolutions reached  $4.4 \times 10^4$  at the respective ranges.

Scoring was detected by the following methods: (a) visual inspection of the tooth faces; (b) measurement of the surface roughnesses along the tooth trace and the tooth profile of the gears; (c) measurements of the bulk-temperature of the mating teeth and the fling-off oil temperature; (d) measurement of the acceleration due to oscillation of the gear box.

To measure the surface roughness along the tooth profile, the feeler set on the tooth profile testing machine was replaced with a thin cantilever in which a diamond needle was attached to the end of a plate spring that was 0.2 mm thick. The surface roughness was detected with a semiconductor strain gage that was attached to the root of the cantilever.

The bulk-temperature of the mating teeth was measured by pressing a contact-type thermister thermometer against the side of the tooth just after the test machine was stopped. Therefore, the bulk-temperature measured was considered to be a little lower than that in running.

The fling-off oil temperature was measured by thermocouples set up at a position opposite the mating position of the pinion. The distance between the hot junction of the thermocouples and the tip of the pinion was approximately 1 mm.

The acceleration due to oscillation of the gear box was

measured by a piezoelectric accelerometer attached to the side of the test gear box.

The measurement of the acceleration due to oscillation was started 1 minute before each end of the respective test ranges, and the acceleration was recorded on the magnetic tape of a data recorder (characteristics of FM : 0 ~ 10 kHz) for about 30 s.

### Test Results and Observations

*Bulk-Temperature of Gear Tooth and Fling-Off Oil Temperature.* For example, Fig. 6 shows the variations in the bulk-temperature of the gear teeth and the fling-off oil temperature with gear pair C (a pinion with the MoS<sub>2</sub> film and a wheel without it) and gear pair D (a pinion without the MoS<sub>2</sub> film and a wheel with it) until surface failure is caused by scoring. In this figure, the symbol S indicates the incipience of surface failure by scoring.

The values of the thermal properties of tooth material and MoS<sub>2</sub> material are shown in Table 7. As evident from equation (4), when the MoS<sub>2</sub> film-coated gear teeth with low thermal properties mate with the gear teeth without it, the rate of the frictional heat flowing into the meshing faces of the gears with the MoS<sub>2</sub> film is less than the gears without it. Thus, the bulk-temperature of the mating teeth coated with the MoS<sub>2</sub> film becomes lower than that of the gears without it.

With gear pair C, the difference between the bulk-temperatures of the mating teeth of the pinion and the wheel was insignificant, and the effect of the MoS<sub>2</sub> film could be recognized on the bulk-temperature of the mating teeth. The bulk-temperature suddenly increased by about 10 K at the incipience of surface failure by scoring. On the other hand, the fling-off oil temperature was higher than the bulk-temperature of the gear teeth.

With gear pair D, in contrast, the difference between the

Table 7 Values of thermal properties of tooth material[2] and MoS<sub>2</sub> material[3]

Material	Thermal conductivity K W/(m K)	Thermal diffusivity $\kappa$ m <sup>2</sup> /s
SCM 415H (373 K)	24	$6.67 \times 10^{-6}$
MoS <sub>2</sub> (373 K)	0.14	$6.88 \times 10^{-8}$

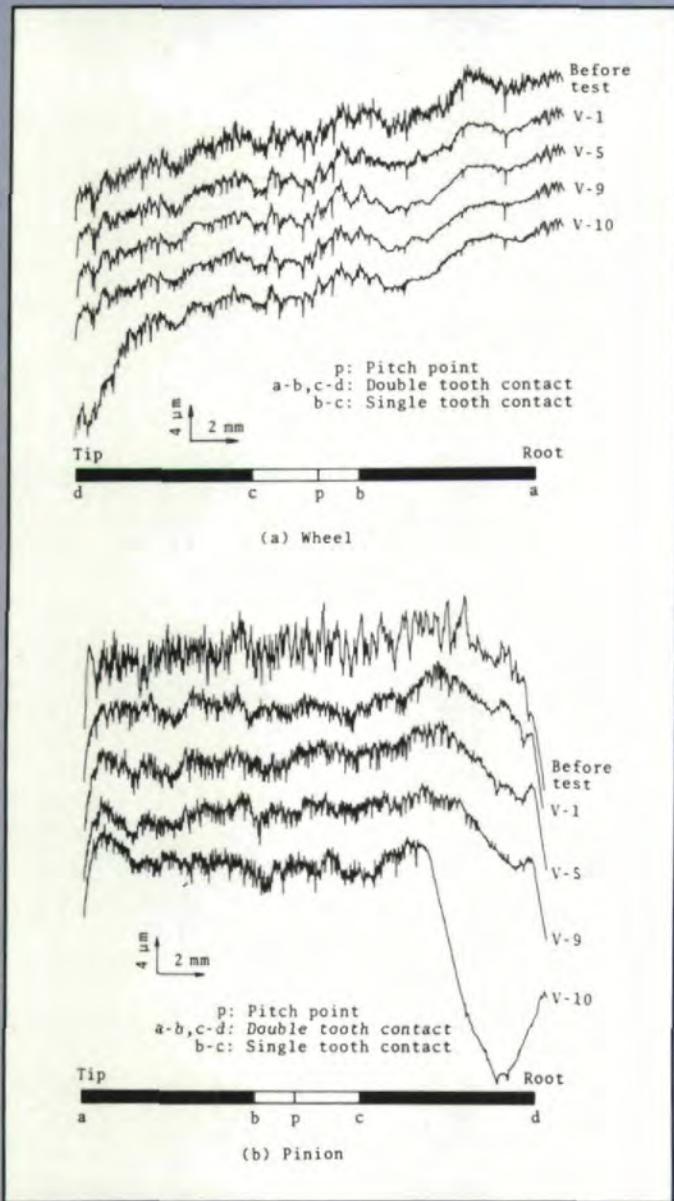


Fig. 7 – Variation in surface roughness along tooth profile with gear pair C

bulk-temperatures of the mating teeth of the pinion and the wheel significantly increased with an increasing test range, and the bulk-temperatures of the pinion was approximately 10 K higher than that of the wheel at the incipience of surface failure by scoring. On the other hand, the fling-off oil temperature was not so much different from the bulk-temperature of the pinion.

**Surface Roughness.** The variation in the surface roughness of the tooth surface along the tooth profile at the

center of the face width with gear pair C is shown in Fig. 7. The variation in the surface roughness of the wheel before surface failure is caused by scoring was considerably small. On the other hand, the depth of a hollow occurring in the vicinity of the root of the pinion considerably increased with an increasing test range. The surface roughness along the tooth profile of the pinion coated with the MoS<sub>2</sub> film before tests was  $8 \mu\text{m } R_{\text{max}}$ , and the surface roughness at the speed range V-1 was  $3 \mu\text{m } R_{\text{max}}$  since the MoS<sub>2</sub> film coated on the tooth surface was torn out due to wear. However, the variation in the surface roughness after V-5 was considerably small.

A destructive surface failure by scoring occurred in the vicinity of the meshing position when the tip of the wheel mated with the root of the pinion. The EHD film thickness, calculated by Dowson's formula, at the meshing position at which destructive surface failure by scoring was observed, is  $0.33 \mu\text{m}$  at V-10. Since the value of  $\lambda^{(4)}$ , defined as the ratio of the film thickness to combined surface texture, is approximately 0.9, the tests were run under mixed lubricating conditions.

For example, Fig. 8 shows the variation in the surface roughness of the tooth surface along the tooth trace in the vicinity of the tip of the wheel with gear pair D. The thickness of the MoS<sub>2</sub> film coated on the tooth surface of the wheel decreased by approximately  $8 \mu\text{m}$  at V-1. After the test range exceeded V-11, the variation in the thickness of the MoS<sub>2</sub> film was considerably small. Surface failure by scoring occurred at the load range P-1, and a part of the base metal

Fig. 8 – Variation in surface roughness along tooth trace in the vicinity of tip of wheel gear pair D

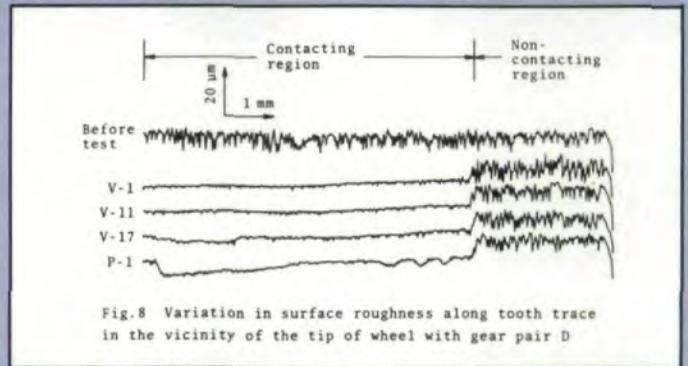
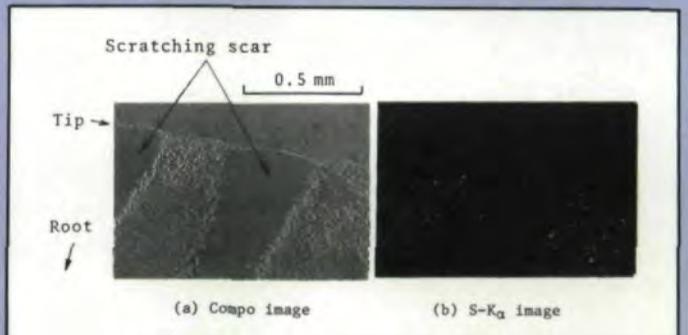


Fig. 8 Variation in surface roughness along tooth trace in the vicinity of the tip of wheel with gear pair D

Fig. 9 – Electron micrographs obtained with scanning X-ray microanalyzer at tip of wheel with gear pair D



(continued on page 30)

# THE LIEBHERR LC 1002

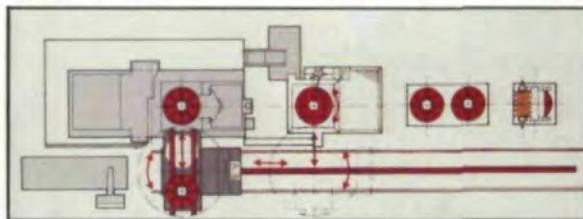
## Innovative Hobbing Machine Technology

### by Design... Not Afterthought

We wanted to do it right. Instead of *adapting* our large capacity hobber for computer control, we started with a fresh sheet of paper to design and build a true CNC hobbing machine. The result: a modern concept for large gear hobbing machines—the versatile and efficient Liebherr Model LC 1002. It automatically cuts gears up to 40" diameter using the industry's latest technological developments. With this integrated design of mechanics and electronics, the LC 1002 gives you a more reliable hobbing system that eliminates time consuming manual settings and protects expensive cutters and workpieces. The LC 1002 will accommodate all modern machining concepts—high speed hobbing, carbide hobbing, skive hobbing, even single index milling.

#### The Liebherr Pallet Shuttle System

Designed for batch sizes as low as *one*, this is the first flexible automation system designed specifically for large CNC hobbing machines. This combination of machine and automation system is available *exclusively* from Liebherr.



Pallet Shuttle System Schematic

The system, with workpiece truing station, storage pallets, and cutter pallet, shuttles cutters and workpieces to and from the machine thereby effecting a complete automatic changeover. Off-machine preparation coupled with high positioning accuracy ensures effortless, precise, safe changeovers. The Liebherr Pallet Shuttle System and the LC 1002 Hobbing Machine—the solution for true automation and flexibility in large hobbing machines.

#### Liebherr, Your Partner for the Future

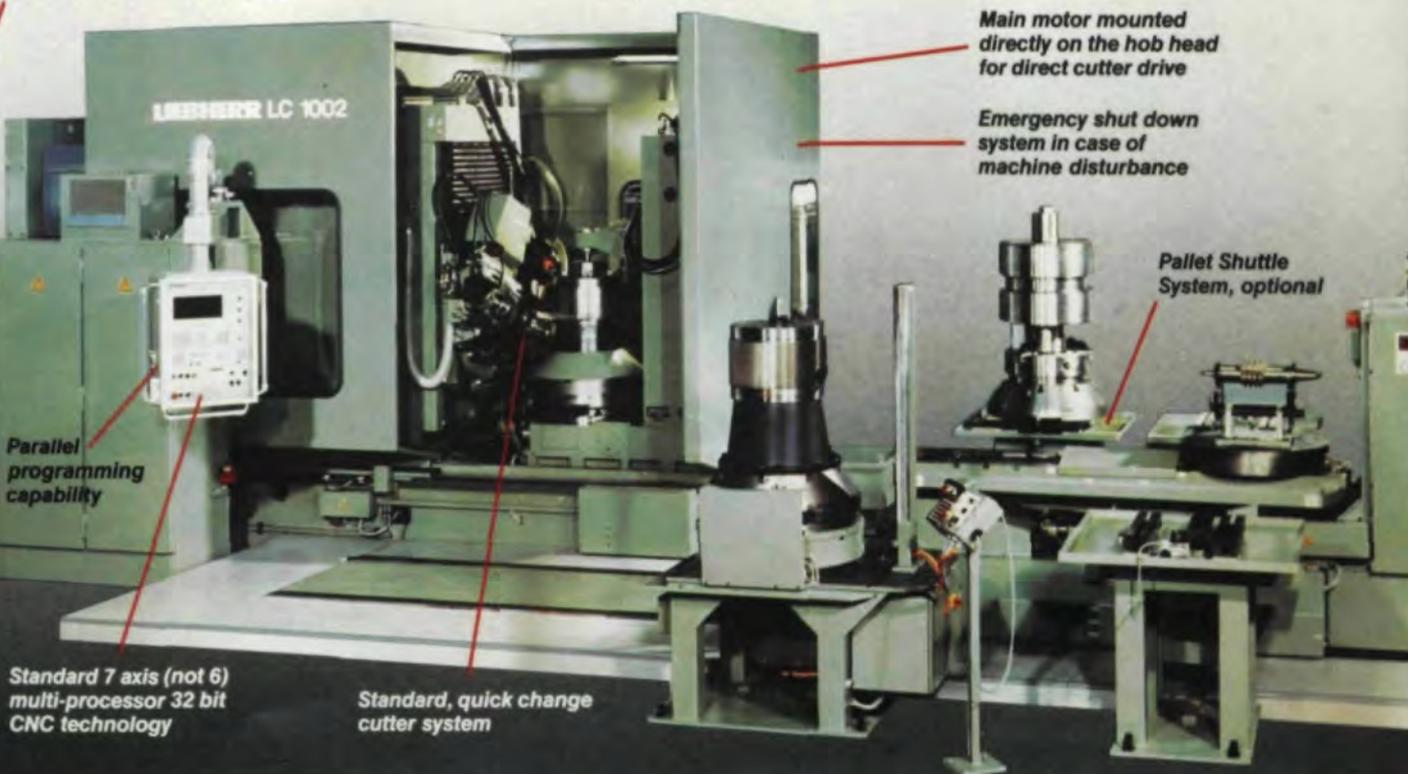
Liebherr is more than gear hobbing, shaping, and flexible automation. Utilizing our total concept capabilities will give you innovative system designs with dependable operation for practical, cost effective manufacturing. Call your partner now,

and remain competitive for the future.

#### LIEBHERR MACHINE TOOL

290 S. Wagner Road, Ann Arbor, MI 48103 Phone: 313/769-3521

Emergency power supply in case of main power failure, optional



Main motor mounted directly on the hob head for direct cutter drive

Emergency shut down system in case of machine disturbance

Pallet Shuttle System, optional

Parallel programming capability

Standard 7 axis (not 6) multi-processor 32 bit CNC technology

Standard, quick change cutter system

# LIEBHERR

trendsetter for gear cutting

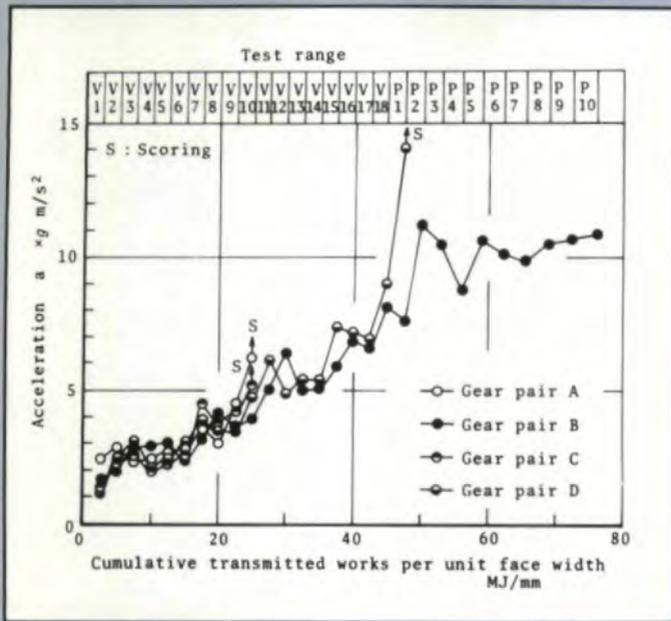


Fig. 10 - Variation in acceleration due to oscillation of gear box

of the gear tooth was exposed on the tooth surface.

Fig. 9 shows electron micrographs of the compo image and the  $S\text{-K}\alpha$  image which were obtained with a scanning X-ray microanalyzer at the tip of the gear tooth of the wheel with gear pair D. The  $\text{MoS}_2$  film at the tip of the wheel was torn out due to wear, and the tooth surface was considerably smooth. However, the particles of sulfur were present at the tooth surface at which the scratching scar did not occur. From this photograph, it can be found the  $\text{MoS}_2$  film is formed enough at the meshing faces at the incipience of surface failure by scoring, and the film significantly affects the scoring resistance of the gears.

**Acceleration of Gear Box.** Fig. 10 shows the variation in the acceleration due to oscillation of the gear box. The acceleration increased with an increasing test range. With gear pair D, the acceleration of the gear box suddenly increased by about 5g at P-1, and the incipience of surface failure by scoring could be detected by means of the measurement of the acceleration due to oscillation of the gear box.

**Surface Temperature and Scoring Resistance.** Fig. 11 shows the variation in the flash temperature rise at the successive meshing positions along the line of action, calculated by equations (1-5) under the following conditions: number of pinion teeth  $z_1=18$ , number of wheel teeth  $z_2=40$ , module  $m=4$  mm, face width  $B_f=7$  mm, backlash  $S_n=0.5$  mm, clearance coefficient  $C_e=0.25$ , tooth load  $P_n=266$  N/mm, pinion speed  $n_1=6000$  rpm.

The surface roughness at the meshing faces and the bulk-temperature of the gear teeth were assumed to be zero. The load-sharing was calculated from the elastic deformation of teeth. In this calculation, Young's modulus  $E$  and Poisson's ratio  $\nu$  of tooth material are assumed to be  $E=206$  GPa and  $\nu=0.3$ , respectively. The coefficient of friction can be given by  $\mu=0.1 V_p^{-0.2}$ , where  $V_p$  is the peripheral velocity (m/s) at the pitch point.<sup>(5)</sup> Since the thickness of the  $\text{MoS}_2$  film coated on the tooth surface is very small, it can

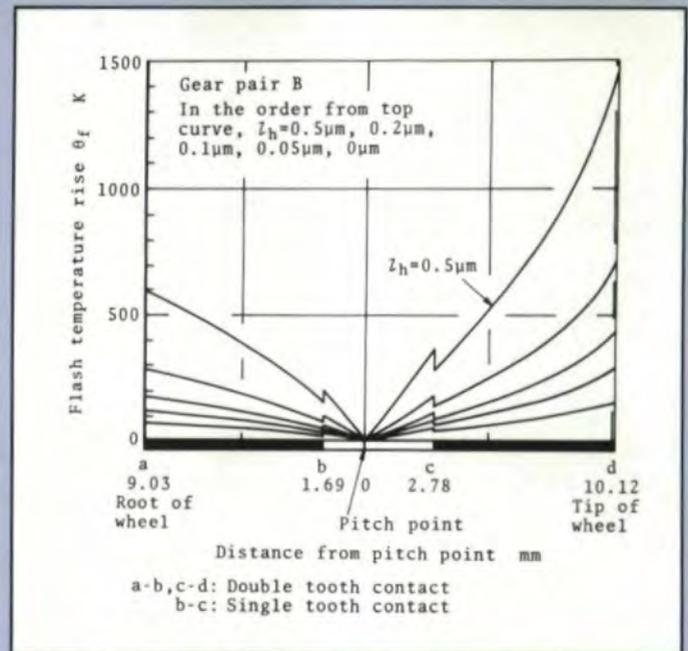


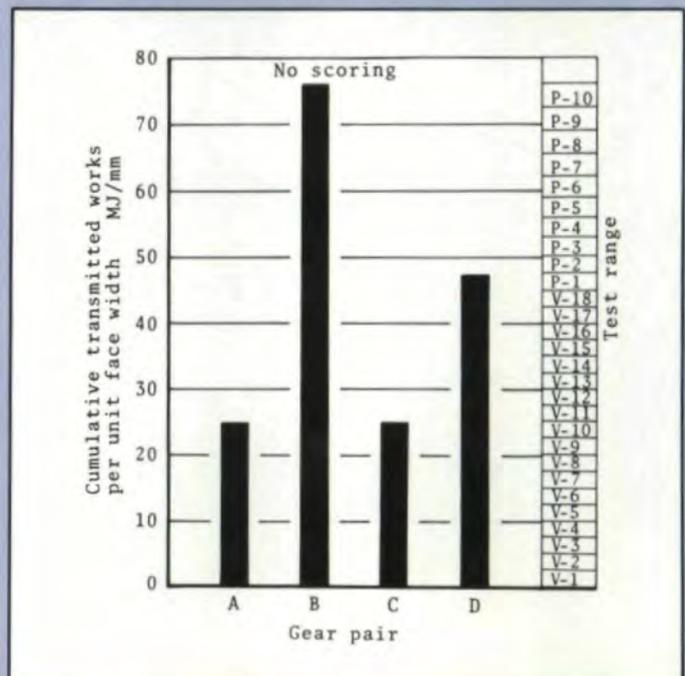
Fig. 11 - Variation in flash temperature rise at successive meshing positions along the line of action

be assumed that the mechanical properties of the  $\text{MoS}_2$  film do not affect the band length of the Hertzian contact zone and the radius of relative curvature of the tooth surface at meshing position of the gears.

From this figure, it can be found that the flash temperature rise considerably increases with an increasing thickness of the  $\text{MoS}_2$  film, and the effect of the  $\text{MoS}_2$  film on the flash temperature rise is significant.

Fig. 12 shows the test range and the cumulative transmitted works per unit face width at the incipience of surface failure

Fig. 12 - Test range and cumulative transmitted works per unit face width at incipience of surface failure by scoring.



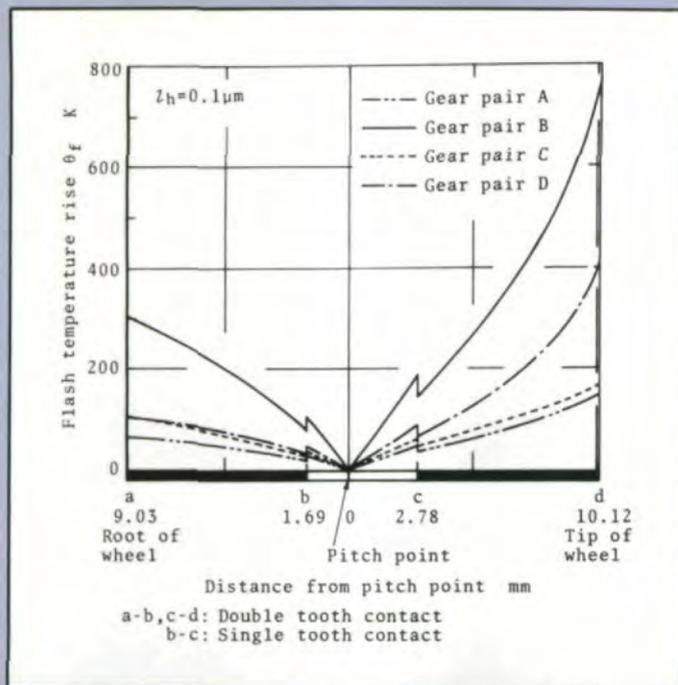


Fig. 13—Variation in flash temperature rise at successive meshing positions along the line of action at incipience of surface failure by scoring

by scoring. With gear pair B, the tests were stopped at P-10 because the scoring resistance of the gears exceeds the load carrying capacity of the test machine. From this figure, it can be seen that gear pair B provides the highest scoring resistance of all test gears, and the MoS<sub>2</sub> film plays a significant role in increasing scoring resistance of the gears. Further, the scoring resistance of the gears with gear pair D is larger than that of the gears with gear pair C, and the MoS<sub>2</sub> film coated on the tooth surface of the wheel is more effective for the scoring resistance of the gears than that coated on the tooth surface of the pinion.

Fig. 13 shows the variation in the flash temperature rise at the successive meshing positions along the line of action at the incipience of surface failure by scoring. The flash temperature rise is calculated by substituting the tooth load, the pinion speed, the coefficient of friction and the thickness of the MoS<sub>2</sub> film into equations (1-5). From the observation

of the sectional plane cut along the tooth profile, it was found that a part of the MoS<sub>2</sub> film was torn out due to wear and the thickness of the film was not uniform on the tooth surface. However, the thickness of the film was assumed to be  $l_h = 0.1 \mu\text{m}$ .

From this figure, it is interesting to note that the maximum value of the flash temperature rise occurs at the meshing position where the tip of the wheel mates with the root of the pinion, and the position well agrees with the position at which destructive failure by scoring was observed.

The critical surface temperature for scoring of the gears is shown in Table 8. The critical surface temperature for scoring of the gears with gear pairs B and D is extremely high because the flash temperature rise of the gears is calculated under the assumptions that the MoS<sub>2</sub> film is uniformly distributed on the tooth surface and the coefficient of friction between the gear pairs coated with the MoS<sub>2</sub> film is equivalent to that between the gear pairs without it. However, a part of the MoS<sub>2</sub> film coated on the tooth surface was torn out just before surface failure was caused by scoring, and the thickness of the film was not uniform on the tooth surface. Further, according to the test results obtained with the four ball tests, the coefficient of friction between the balls coated with the MoS<sub>2</sub> film was smaller than that between the balls without it.

From the above cited facts, it can be considered that the critical surface temperature for scoring of the gears coated with the MoS<sub>2</sub> film is lower than the value shown in Table 8. However, the scoring resistance of the gears coated with the MoS<sub>2</sub> film is considerably large, and the MoS<sub>2</sub> film is considered to play a significant role in increasing scoring resistance of the gears.

### Conclusions

Calculated surface temperatures and the experimental results obtained with four ball tests and gear tests with respect to the effect of the MoS<sub>2</sub> film on the scoring resistance of the gears are summarized as follows:

1. When the thickness of the surface layer is smaller than the band length of the Hertzian contact zone, the effect of the thermal properties in the surface layer on the flash temperature rise is significant, and the difference between the

Table 8 Critical surface temperature for scoring of gears

Gear pair	$R_{rms}^{(a)}$ $\mu\text{m}$	Bulk-temperature <sup>(b)</sup> $\theta_0$ K	Maximum flash temperature rise $\theta_f$ K	Critical surface temperature <sup>(c)</sup> $\theta_{cr}$ K
A	0.33	340	148	540
B <sup>(d)</sup>	(0.37)	(351)	(770)	(1438)
C	0.36	337	167	570
D	0.48	346	411	1007

(a)  $R_{rms}$  is the mean value of the root mean square roughness along the tooth trace of the pinion and wheel just before scoring.

(b)  $\theta_0$  is the mean value of the bulk-temperature of the gear teeth of the pinion and wheel just before scoring.

(c)  $\theta_{cr} = \theta_0 + \theta_f \times 1.27 / (1.27 - R_{rms})$  [6]

(d) The numerals in parentheses are the value of the variables at P-10.

# BEVEL GEAR MACHINERY SERVICE



**Complete, nationwide services exclusively for spiral, straight and hypoid generators, testers and grinders.**

- No cost equipment evaluations
- On-site maintenance and repair
- Complete machine rebuild to factory specifications
- Guarantee on all service and repair



Brad Foote Gear Works, Inc.  
1309 South Cicero Avenue  
Cicero, IL 60650  
312/242-1070

CIRCLE A-11 ON READER REPLY CARD

thermal properties in the surface layer and those in the core is an important problem.

2. Under comparatively low load ( $P < 0.4$  kN), the coefficient of friction between the balls coated with the  $\text{MoS}_2$  film was 2/3 of that between the balls without it.

3. The scoring resistance of the gears coated with the  $\text{MoS}_2$  film is considerably large, and the  $\text{MoS}_2$  film plays a significant role in increasing scoring resistance of the gears. The development of the gears of which the load-carrying capacity against scoring is considerably large could be made.

#### References

1. BARTZ, W. J., "Some Investigations on the Influence of Particle Size on the Lubricating Effectiveness of Molybdenum Disulfide," *ASLE Trans.*, Vol. 15, 1972, pp. 207-215.
2. TERAUCHI, Y., MIYAO, Y., and NADANO, H., "On the Flash Temperature Rise of the Tooth Surface of Surface-Hardened Gears," *Bulletin of the JSME*, Vol. 16, No. 99, 1973, pp. 1443-1456.
3. YAMAMOTO, T., and HANADA, H., "Manufacturing Process of Solid Lubricants," *Jour. Japan Soc. Lub., Engrs.* (in Japanese), Vol. 27, No. 4, 1982, pp. 233-237.
4. WELLAUER, E. J., and HOLLOWAY, G. A., "Application of EHD Oil Film Theory to Industrial Gear Drives," *ASME Journal of Engineering for Industry*, Vol. 98, No. 2, May 1976, pp. 626-634.
5. ISO TC60/WG6, "Calculation of Scoring Resistance," Dutch-Swiss draft, May 1977.
6. TERAUCHI, Y., and NADANO, H., "Effect of Tooth Profile Modification on the Scoring Resistance of Spur Gears," *Wear*, Vol. 80, 1982, pp. 27-41.

This article was presented previously at the ASME Design Engineering Conference, October 1984. Paper No. 84-DET-59.

Frödenberger  
Maschinen- und  
Apparatebau GmbH  
W-Germany

our representative  
R. J. Kemp  
and associates SAE  
38 W 510 Lake Charlotte Ct  
St. Charles, IL 60174  
Tel. 312-584-4488



## Nobody

is able to deliver  
Keyseating Machines with  
more possible applications  
for comfort and ease of  
set-up!



In the margin, you can  
see one of thousands of  
special solutions we offer  
our customers: machining  
a keyway in a blind hole  
with high precision using  
a guided tool.

We offer other applica-  
tions such as: tapered  
keyways, tapered, inter-  
rupted or stepped bores;  
also internal multi-splines,  
internal gearing and copy-  
ing keyways. Visit us at  
IMTS.

Mc CORMICK PLACE WEST  
LEVEL 2  
BOOTH 8818

**IMTS**  
The world of manufacturing technology  
1986 INTERNATIONAL MACHINE TOOL SHOW  
September 3-11, 1986 • Chicago, Illinois, USA