Management Summary

A study was conducted on the development of a CNC gear measuring machine for measuring involute tooth profile by a new measurement method. Involute tooth profile measurement has been done, until now, by almost always using two-axis control in which the probe moves only in the X-axis direction synchronously with the gear rotation angle ($\theta$).

In contrast, the newly developed measurement method uses three-axis control in which the probe moves along the line of action under control in two orthogonal, axial directions (along the X and Y axes) synchronously with the gear rotation angle ($\theta$).

This new method enables high-accuracy measurement because the small X-direction movement of the probe reduces the guaranteed accuracy range and minimizes movement of the probing head gravity center. As probe movement in the X-direction is unaffected by gear outside diameter, the advantage of the new method over earlier ones is particularly relevant to the measurement of super-large gears. While conventional measurement methods must use multiple probes to avoid probe-tooth interference in the measurement of inner gears, the new method uses fewer probes in inner gear measurement and eliminates the need for an automatic tool changer (ATC). In the case of a small-diameter inner gear (outside circle diameter of 10 mm or less), measurement of tooth profile, helix and pitch deviation can be completed with a one-time setting. A CNC gear measuring system is developed using this new measurement method that provides numerous advantages over conventional measuring systems.
Introduction

Almost without exception, conventional dedicated gear measuring machines measure involute tooth profile by the two-axis control method: the probe moves only along the X axis, orthogonal to the axis of rotation synchronously with the gear rotation angle (θ) (Figs. 1–2). As it is based on the principle of involute tooth profile generation, this conventional method is quite simple and easy to understand.

However, the working positions in the hobbing machine, gear shaper, gear grinder and other tooling are almost all near the center of the gear, and these working positions are very different from the conventional tooth profile measurement positions. In the hobbing machine, the tooth cutting position of the hob cutter moves along the gear line of action while rotating synchronously with the gear blank (Fig. 3).

The author long questioned the reason for the significant difference between the working positions during gear machining and the measurement positions during gear measurement (tangent to the base circle). This current study grew out of an intuition that it should work to control the probe movement at the gear cutting position.

The author will use the term “tangential direction generate method” (TDG Method) for the ordinary measurement in which the probe moves only in the direction tangential to the base circle (X-axis direction orthogonal to the axis of rotation), and the term “normal direction generate method” (NDG Method [patent applied]), for the new measurement method in which the probe moves along the lines of action (X and Y axes orthogonal to the axis of rotation).

Normal Direction Generate Method (NDG Method)

Amount of probe movement. As seen in Figure 3, the NDG Method measures tooth profile as the probe is moved along the line of action in the same way as the hob cutter during tooth cutting. The probe moves in the direction of touching the base circle, and the principle of involute tooth profile generation is exactly the same as in the TDG Method.

Measurement of a standard gear without any profile shift (whose height of the involute tooth profile portion is one module on both the addendum side and the dedendum side) by the NDG Method gives

\[ L_a = L_d = \frac{m}{\tan \alpha_t} \text{ (mm)}, \]

where \( L_a \) and \( L_d \) are the amounts of probe X-axis direction movement from the Y axis passing through the gear center on the addendum side and the dedendum side, respectively; \( m \) is the module (mm), and \( \alpha_t \) is the transverse pressure angle. When \( \alpha_t = 20^\circ \), \( L_a = L_d \approx 2.7 \text{ m} \). Measurement is the same for the right and left tooth faces. Thus the amount of probe movement in the NDG Method is independent of the number of gear teeth and diameter of the reference circle.

On the contrary, the amount of X-axis direction probe movement in the TDG Method is approximately proportional to the reference circle diameter (Fig. 4) and given by:

\[ L_t = L_r = 0.5z \cdot m \sqrt{\left(1 + \frac{2}{z}\right)^2 - \cos^2 \alpha_i} \]

A graph representing \((L_t + L_r)\) when \(m = 10 \text{ mm}\) is shown in Figure 5. The amount of X-axis direction probe movement increases with the diameter of the reference circle. A machine capable of measuring a super-large gear like that in Figure 6 using the TDG method is therefore very difficult to build.

Measurement error. While probe movement is solely in...
the X-axis direction during tooth profile measurement by the TDG Method, it occurs in both the X-axis and Y-axis directions of the measuring machine in the NDG Method. The profile measurement error caused by probe movement error during measurement therefore differs between the TDG Method and the NDG Method. The nature of this difference was investigated.

In Figure 7, the probe being positioned at A indicates tooth profile measurement by the TDG Method, and the probe being positioned at B indicates tooth profile measurement by the NDG Method.

Let us assume that maximum tooth profile measurement error in the TDG Method, designated \( F_{\alpha-TDG} \), can be expressed by:

\[
F_{\alpha-TDG} = |e_X| + |e_L| + |\Delta \theta| r_b \quad (1)
\]

where:
- \( |e_X| \) is the maximum X-axis direction error of the probe arising independently of its X axis position,
- \( |e_L| \) is the maximum X-axis direction error of the probe arising due to large movement of the probe,
- \( |\Delta \theta| \) is the maximum gear rotation angle error,

and:
- \( r_b \) is the radius of the gear base circle.

Let us further assume that maximum tooth profile measurement error in the NDG Method, designated \( F_{\alpha-NDG} \), can be expressed by:

\[
F_{\alpha-NDG} = |e_X| \cos \alpha_t + |e_Y| \sin \alpha_t + |\Delta \theta| r_b \quad (2)
\]

As the amount of probe movement is small in the NDG Method, \( |e_L| \) is assumed to be negligibly small.

The maximum tooth profile measurement errors by the NDG Method and TDG Method are compared by taking the difference between Equation 1 and Equation 2 to obtain Equation 3:

\[
F_{\alpha-NDG} - F_{\alpha-TDG} = |e_X| \cos \alpha_t - 1 + |e_Y| \sin \alpha_t - |e_L| \quad (3)
\]

From the fact that \( |e_Y| \) is about the same size as \( |e_X| \), the following expression holds:

\[
F_{\alpha-NDG} - F_{\alpha-TDG} \approx |e_X| \sin \alpha_t + \cos \alpha_t - 1 - |e_L| \quad (4)
\]

when:
- \( \alpha_t = 20^\circ \),

\[
F_{\alpha-NDG} - F_{\alpha-TDG} \approx 0.28 |e_X| - |e_L| \quad (5)
\]

This means that the tooth profile measurement error of the TDG Method is greater than that of the NDG Method when \( |e_X| \ exceeds 0.28 |e_L| \).

To give a specific example: at \( |e_X| = 0.2 \mu m \), the TDG Method becomes greater in measurement error than the NDG Method.

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**Figure 4**—Amount of probe movement by TDG Method.

**Figure 5**—Amount of probe movement in X-axis direction by TDG Method.

**Figure 6**—TDG Method measuring machine for a super-big gear.

**Figure 7**—Measurement error by TDG Method (A) and NDG Method (B).
indicates measurement of inner gear tooth profile by the TDG Method. When a probe of small tip diameter is used, interference occurs between the tooth tip and the probe stem. If an attempt is made to avoid interference between the tooth tip and probe stem by enlarging the probe tip diameter, interference will then occur between the probe tip and the opposite tooth face. Although this problem can be overcome by removing one side of the probe tip, it would require the probe orientation to be reversed laterally when measuring the opposite tooth face.

On the other hand—as shown in Figure 8B—measurement by the NDG Method does not experience interference between the tooth tip and probe, no matter how much probe tip diameter is reduced. The left and right tooth faces can therefore be measured with a single, small probe. The efficacy of the NDG Method is therefore particularly evident in the measurement of small-diameter, inner gears ($\phi \leq 10$ mm or less).

**Probe tip position.** It should also be noted regarding measurement by the NDG Method that it differs from that of the TDG Method not only in the direction of probe movement, but also—depending on the probe type—in the initial probe position.

Figure 9 shows an example in which the probe has a spherical tip. In the TDG Method—indicated by A in the drawing—the center of the tip sphere is positioned on the X axis, where the measurement is performed. In the NDG Method—indicated by B in the drawing—the center of the probe tip sphere is positioned at the intercept of the reference circle and the Y axis, and measurement is performed along the line of action at pressure angle $\alpha_t$.

Figure 10 shows an example in which the probe has a chisel type tip. In the TDG Method—indicated by A in the drawing—the tip of the chisel is positioned on the X axis, where the measurement is performed. In the NDG Method—indicated by B in the drawing—the axis of the probe stem is aligned with the Y axis and the chisel tip must be moved from the intercept of the reference circle and the Y axis toward the gear center by $(d_p/2)\tan \alpha_t$, where $d_p$ is the tip diameter of the
chisel type probe.

**NDG Measuring Machine**

A measuring machine utilizing the newly developed NDG Method is shown in Figure 11. The specifications of the developed measuring machine are provided in Table 1. The X axis direction width of the measuring machine can be slimmed down considerably, compared with one adopting the conventional system.

In the measuring machine using the NDG Method, the probe is controlled in orthogonal, two-axis (X and Y) direction at a given angle to move along the line of action. It should therefore be noted that the tooth profile error output of the probe—which has sensitivity in the X axis direction—is the cosine (cos) of the transverse pressure angle. In other words, the tooth profile error must be multiplied by the displacement output (1/cosα). And, as mentioned previously, the probe must be initially positioned so that the measurement point falls on the line of action.

**Measurement Result**

The dimensions of a gear for test measurement are shown in Table 2.

NDG Method measurement is performed near the gear center, analogous with the working positions in a gear manufacturing machine. This makes measurement possible in a much shorter time than by the TDG Method. A comparison of measurement times using the same developed measuring machine showed that the NDG Method achieved a time reduction of 35% for profile measurement, compared with the TDG Method.

Figure 12 and Table 3 show the results when tooth profile measurement is conducted by the NDG Method and TDG Method in the same developed measuring machine. The results show that there is no substantial difference in measure-
ment accuracy between the NDG Method and TDG Method.

Conclusion

The following are some typical problems that arise when tooth profile is measured by the conventional TDG Method, in which the probe moves only in the X axis direction:

- High-accuracy measurement cannot be anticipated in a measuring machine for large gears because the large movement of the probing head expands the guaranteed accuracy range and increases movement of the probing head gravity center.
- The X axis direction movement of the probe is proportional to the gear reference circle diameter, making large-gear measurement time consuming.
- When an inner gear is measured, it is often impossible to measure tooth profile, helix and pitch deviation with a one-time setting because interference arises between the tooth face and probe, thus necessitating frequent interruptions.
- Numerous probes matched to different gear sizes are necessary. An automatic tool changer is therefore more often required, and probe calibration work increases.
- Measurement of a small-module inner gear (minimum outside circle diameter of 10 mm or less) is difficult.

![Figure 12—Profile measurement results by TDG Method and NDG Method.](image)

- High-accuracy tooth profile management is hard to achieve in the measurement of dies and molds used for plastics, sintered metals, forgings and the like.

In contrast, advantages such as the following are obtained when tooth profile measurement is performed by the NDG Method, in which the probe moves along the line of action under control in two orthogonal, axial directions (along the X and Y axes):

- High-accuracy measurement is possible, even in a measuring machine for large gears, because the small X axis direction movement of the probe reduces the guaranteed accuracy range and minimizes movement of the probing head gravity center.
- As measurement is conducted near the gear center, even a large gear with a large reference circle diameter can be measured in a relatively short time.
- In inner gear measurement, the fact that no interference arises between the gear and the probe reduces the number of probes required, eliminates the need for an automatic tool changer, and minimizes probe calibration work.
- Measurement of tooth profile, helix and pitch deviation can be completed with a one-time setting, even in the case of a small-diameter inner gear (outside circle diameter φ of 10 mm or less).

A program enabling NDG Method measurement can be incorporated into an existing CNC gear measuring machine. When an NDG Method measuring machine was actually built, it was found that the X-axis direction width of the machine could be made slimmer than a conventional one. In addition, the tooth profile measurement results were found to be substantially no different in accuracy from those by the conventional system. The NDG Method was incorporated into a conventional measuring machine and was confirmed to be a tooth profile measuring method applicable to gears ranging widely in size—from super-large to miniature.

(In closing, the author wishes to express heartfelt gratitude to the team members who built the measuring machine.)

Masatoshi Yuzaki is president of Tokyo Technical Instruments, a company he founded in 1972 as a manufacturer of gear measuring machines and instruments. Yuzaki’s continuing commitment to the development of innovative products that contribute to gear quality improvement worldwide is evidenced by his company’s many and diverse offerings matched to ever-changing global measurement needs. Applications have been filed for international patent protection of the NDG Method measuring machine. Yuzaki is a member of the Measurement Committee of the Japan Gear Manufacturers Association (JGMA) and a member of the Japan Society of Mechanical Engineers (JSME).